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Towards Generalizing Visual Process Patterns

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Abstract: Visual Process Patterns (VPP) is a visual language to describe constraints on the behavior of UML Activities. They have been developed for the sake of formulating and verifying requirements on business process models in a visual, intuitive way (with UML Activities being one possible description language). In the VPP approach, a visual process pattern is translated into an LTL formula, which can then be verified against a transition system describing the behavior of the Activity under consideration.

In this paper, we aim at generalizing VPP. We show how to formulate patterns more generally, using an enhanced version of the concrete syntax of the behavioral model under consideration. Additionally, we describe how these more general patterns can be verified against a model’s behavior.

Keywords: Pattern, semantics, verification, business process, activity, state machine

1 Introduction

Business processes are a crucial part of many companies’ business, and therefore have to fulfill certain domain specific and quality requirements. Such requirements can e.g. be specified by means of so-called process patterns. For instance, such a process pattern can state that “after each production action a quality check has to be performed prior to delivery”.

Given the complexity of many business processes, it would be desirable to be able to automatically verify such requirements against a particular business process. This implies that the modeler has to somehow formalize the requirements.

Unfortunately, the semantic gap between a visual, flow-oriented business process model and most formal specification languages (e.g., temporal logic [CES86]) is quite large. Therefore, the translation of (informal) requirements into a (formal) specification language is a challenging task, and must be expected to be beyond knowledge of the average business analyst.

Visual Process Pattern (VPP) [För08] aim at bridging that semantic gap by allowing the business analyst to model the requirements in basically the same language as the business process itself. In the case of VPP, the underlying modeling language is UML Activities [Obj09]; its fitness for business process modeling is obvious. See Fig. 1 for an example business process from the insurance domain, modeled as a UML Activity.

Consequently, Förster et.al. [FESS07, FSES06, FES05] have suggested an Activity based visual language which allows for the specification and verification of requirements like “After each production action, a quality check has to be performed prior to delivery”. Figure 2 gives a first impression of a VPP representation of that requirement, which will serve as a running example for the rest of this paper; more details of VPP will be explained in Sect. 2.
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![Diagram of a business process as a UML Activity](image.png)

**Figure 1:** Example business process, modeled as a UML Activity

**Figure 2:** Visual process pattern formalizing the requirement “After each production action a quality check has to be performed prior to delivery”

Förster’s approach is well-suited for the formulation of requirements put on UML Activities and the execution of the contained Actions, but it does not allow for the formulation of requirements about other Activity constructs (e.g., whether a token has arrived at a FinalNode) or even against other languages (e.g., UML State Machines). This is due to the fact that Förster’s language is dedicated to formulating requirements against UML Activities only. As a consequence, UML Actions (i.e., the places in an Activity where actual work takes place) are an important element of that language. As a result, the language is not able to express requirements against models which do not contain Actions (e.g., models which are not UML Activities).

In this paper, we describe how to generalize the VPP approach to be able to do exactly that. We will show how to formulate and verify requirements on arbitrary languages. For that, we will reuse a part of Förster’s language. The basic idea is to replace Actions in a VPP with arbitrary states of execution of the underlying model, and to connect these states with the flow elements used in VPPs. The states of execution of the underlying behavioral model can be described in concrete syntax.

*Structure of paper:* In the next section, we will give more insight into the VPP approach. We will point out some technical details of VPP and demonstrate them using the running example introduced above. Based on that, Sect. 3 will then show how the VPP approach can be generalized such that requirements can be formulated and verified against arbitrary language constructs. Section 4 presents work related to our approach, and the last section concludes and points out the current state and the future of our work.

## 2 Visual Process Pattern

We have mentioned in the introduction that a VPP is expressed as a number of Actions, connected by custom flow elements (we have seen an example in Fig. 2). In this section, we want to precisely define the example’s semantics, and we want to shed light on the technical background of VPP.
We start with an assumption, though: We expect to receive the semantics of a business process model as a labeled transition system (LTS), where the labels contain information about the model’s execution. A trace through such an LTS is the sequence of labels we get on one of the possible “ways” through the LTS. We will later see how this is actually realized in the VPP approach, and how to use this fact for generalizing the approach.

The idea of VPP is to visually describe temporal properties of a model. For instance, one wants to express that “when Action A is executed, Action B will be executed at some point in the future”. The interested reader will immediately see that the temporal part of the above statement (“when event A, then eventually event B”) can easily be expressed using temporal logic.

This is indeed what the VPP approach does: in [FESS07], the authors have defined the visual pattern language by mapping the custom flow elements into the temporal logic dialect LTL. For instance, the example VPP depicted as Fig. 2 is translated into the two formulas $G(\text{produce} \rightarrow F \text{test quality})$ and $G(\text{ship} \rightarrow Y \text{test quality})$. Figure 3 shows the whole underlying process.

In LTL, expressions about paths $G$ stands for “all future states”, $F$ means “some future state”, and $Y$ translates to “the previous state”. It now becomes clear how the formulas are related to our example VPP: The first expression is true for a trace of the LTS, if for all the trace’s states it is the case that if label $\text{produce}$ occurs, label “test quality” will occur in the future. The second expression is true for traces such that if label “ship” occurs, label “test quality” must have been the previous label. Note that an expression is true for an LTS iff it is true for all (possibly infinite) traces through that LTS.

So far, we have seen how to express VPPs into according LTL formulas which can then be verified against an appropriately labeled transition system. Our next step will be the generation of such an LTS. This is where Dynamic Meta Modeling comes into play.

### 2.1 Dynamic Meta Modeling

Dynamic Meta Modeling (DMM) [Hau05] is a semantics specification technique targeted at visual behavioral modeling languages whose abstract syntax is defined by means of a metamodel. The idea of DMM is to enhance such a given metamodel with concepts needed to express states of execution of a language’s model, leading to a so-called runtime metamodel. In a second step, operational rules are defined which describe how instances of the runtime metamodel (i.e., models in a certain state of execution) change in time (i.e., which state(s) of execution will be
reached from a certain state according to the language’s behavior). Such a DMM rule has a precondition which must be fulfilled for the rule to match; if this is the case, the rule is applied, leading to a new state. The DMM approach is depicted as Fig. 4.

Let us illustrate the above using the example language of UML Activities: The runtime metamodel of UML Activities adds concepts such as an ActivityExecution class, a Token class, etc., whereas the operational rules describe how tokens flow through an Activity during execution. For instance, one of the mentioned DMM rules makes sure that an Action is executed if all its incoming edges carry at least one token. If this is the case, the Action starts execution.

A DMM specification together with an instance of the runtime metamodel give rise to an LTS, where states are states of execution of the according model, transitions are applications of operational rules, and labels are names of operational rules. The instance of the runtime metamodel serves as the start state of the LTS. The LTS can then be analyzed with model checking techniques, e.g. to verify LTL formulas as defined above: The idea is to refer within these formulas to the names of appropriate DMM rules corresponding to the desired states of execution (e.g., the execution of a particular Action).

Technically, DMM is based on graph transformations [EEKR99]. The instances of the runtime metamodel are treated as (typed) graphs, and the DMM rules manipulate these graphs. As a result, DMM specifications are not only formal, but also easily understandable due to their visual nature. The execution of DMM specifications as well as the model checking are performed using the GROOVE tool set [Ren04, KR06], an excerpt of the resulting LTS is depicted as Fig. 5. See [Hau05, För08] for more details on DMM and the way VPPs make use of it.

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Note that since UML 2.0, the semantics of Activities is based on token flow.
3 Generalization of VPP

In the last section, we have seen how VPPs are translated into temporal logic formulas which can then be model checked against the LTS derived from the language's semantics specification and the business process itself (which serves as the start state). We have also seen how VPP uses DMM: For every Action of the business process, a corresponding DMM rule exists; the according label in the LTS corresponds to the execution of the according rule.

However, as mentioned earlier, this approach does not help if we e.g. want to formulate requirements on other language elements than Actions, let alone other behavioral languages. This is not possible with VPPs since the usage of Actions is “hardcoded” into the approach, as we have seen earlier. For instance, we would like to be able to express requirements like “When Action A is executed, the Activity will always terminate properly”. However, the VPP language does not contain any constructs allowing to express requirements on other elements than Actions.

One solution could be to directly refer to rules of the semantics specification within a VPP expression. For instance, instead of connecting Actions with the VPP flow elements (as seen in Fig. 2), we could connect a representation of the rules corresponding to the behavior of interest. However, this has two serious drawbacks: First, the business analyst creating the VPPs needs to have knowledge about the rules contained in the semantics specification: Which rules do exist, and which situations do they correspond to? Second (and even worse), we would also like to be able to express requirements about states of execution of our model for which no corresponding rule exists. For instance, we might want to express that at some point in time, both Actions A and B are executed in parallel; however, there is no corresponding rule for that kind of requirement.

Fortunately, GROOVE offers the concept of so-called property rules. The next section will show how these property rules can be used to formulate requirements about a much broader class of states of execution.

![Diagram](image.png)

Figure 5: Excerpt of the transition system resulting from the example business process in Fig. 1, generated using DMM and GROOVE
3.1 Property Rules

Property rules are rules which have a precondition, but they do not change the states they are applied to. In other words: if such a rule matches a state, the rule is applied, leading to a self-transition of the according state. Technically, a property rule is a graph transformation rule having the same left-hand and right-hand graphs.

These property rules can be used for our goal of formulating requirements in a more flexible way: For every state property of interest, an according property rule is defined and added to the DMM ruleset. For instance, if we are interested in the state where Actions A and B are executed in parallel, we just need to create a property rule describing exactly that situation: The rule would contain the according Actions which would both carry a token, corresponding to the fact that they are both executed.

The resulting LTS will contain some additional transitions: Every state which fulfills the formulated property will have a label with the property rule’s name. This allows for the verification of temporal formulas about those properties as described in Sect. 2. Note that the new LTS will be stuttering equivalent to the original transition system, i.e., if we remove all occurrences of property rules from the traces of our new LTS, the resulting set of traces is equal to the set of traces of the original LTS. To put it differently: Adding property rules to an existing ruleset does not significantly change the ruleset’s semantics.

Note also that using property rules still allows to verify all requirements formulated with “plain” VPPs as described by Förster. This is done by deriving property rules from the DMM rules used within the verification process in a trivial way. For each DMM rule used in the verification process (i.e., each rule referenced by our original VPPs), we introduce a new property rule whose precondition is fulfilled if the according Action is executed. If we compute the LTS, every state which was labeled with one of the original rules will additionally be labeled with the according property rule. This means that we can still check the requirement by using the same LTL formulas as before; the only difference is that the rules referenced within these formulas have been replaced with the corresponding property rules.

3.2 Specification of State Properties

But how to specify property rules? Our assumption is that the business analyst knows the semantics of the modeling language used (otherwise she will probably not be able to come up with a meaningful model). Therefore, it seems reasonable to use a concrete syntax of the runtime metamodel for specifying the property rules, since we want their appearance to be as close to the original language as possible.

Let us illustrate this with a small example in the domain of Activities: We have seen above that the semantics of Activities is based on token flow, and that the DMM runtime metamodel of UML Activities therefore contains a Token class. An obvious visualization of the Token concept is a black, filled dot which is drawn at the language element the token is located. Figure 6 shows an example property rule: The rule matches if a token is sitting at an ActivityFinalNode.

Besides being intuitive and easily understandable, the suggested representation of property rules has another advantage: Having a concrete syntax for the runtime part of the language allows for the (animated) visualization of the execution of a model, e.g. for using it within a
3.3 Formulating VPPs Using Property Rules

It is now straightforward how to use property rules within a VPP. Instead of referring to a concrete Action within one of the boxes contained in the VPP, a property rule is used which describes the properties of the state of interest. Figure 7 shows such a VPP realizing the requirement “When Action A is executed, the Activity will always terminate properly”: the left Action of the VPP contains Action A carrying a token (corresponding to that Action being executed), the right part shows a FinalNode carrying a token (corresponding to the whole Activity being terminated).

Of course, the boxes can still be connected using the flow elements contained in the VPP language (as we did in Fig.7). As a result, the translation to temporal logic nearly remains unchanged. The only difference is that instead of using a reference to an existing DMM rule within a VPP, the according property rule is referenced.

Finally, it is now easy to see how this approach can be used for formulating requirements against other behavioral languages: for instance, in the case of UML State Machines, the runtime metamodel will most likely contain the concept of a “marker” which shows the current state(s) the machine is in. Having a concrete syntax for that marker concept, the marker can then be used to formulate requirements like “When the State Machine is in state A, it will eventually be in state B”.

4 Related Work

The related work of this paper mainly falls into two categories: workflow and process patterns and the verification of formal properties against workflows and processes.

Workflow and Process Patterns Van der Aalst et.al. [AHKB03] have suggested a number of workflow patterns describing several types of control flow structures in workflow systems. Using Petri nets, their main focus was to identify typical control flow structures contained in workflows, and to use this knowledge to assess existing workflow management systems and workflow specification languages for expressiveness. Ambler [Amb96] suggests the application of process patterns to software development processes; however, his approach does not contain a formal underpinning which could be used for automatic verification of such processes.
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Verification of Workflow and Process Properties  Kindler and van der Aalst [KA99] describe how to verify Petri Nets for general properties like soundness and liveness, but their approach does not support the verification of user-defined properties raising e.g. from domain-specific requirements. Janssen et.al. [JMM+99] suggest an approach for the verification of business processes using model checking techniques which is based on a proprietary process modeling language. The authors formalize different basic constraints; again, the approach does not allow for the verification of custom, user-defined properties.

5 Conclusion

In this paper, we have shown how to generalize the VPP approach, which deals with the visual specification of formal requirements against business processes. For this, we have briefly introduced the VPP approach, and we have explained how DMM and GROOVE are used to perform the verification of such requirements in Sect. 2.

Based on that, we have shown in Sect. 3 how to replace the “hard-coded” Action rules of the DMM approach with so-called property rules, i.e., rules which do not change states they are applied to, but are still represented as labels in the resulting LTS. We have shown how to formulate the property rules using a concrete syntax of the runtime metamodel which is part of the DMM specification. To demonstrate our approach, we have shown how to reformulate existing VPPs using property rules, and we have provided a simple process requirement which could not be formulated using the existing VPP language, but can be formulated with our approach. Additionally, we have described how to compose property rules to requirements on the whole LTS, borrowing the flow constructs and their mapping to LTL from Förster’s VPP approach.

Future Work  We are currently working on incorporating the described approach into our DMM tooling. This involves several steps: First, we need to investigate a reasonable way to define a concrete syntax for a runtime metamodel as used in the DMM specification technique (given that the syntax metamodel of the language is already equipped with a concrete syntax).

Additionally, as mentioned earlier, we plan to reuse the concrete syntax of the runtime metamodel for a visual debugger for languages having a DMM specification. The general idea is to animate the execution of a behavioral model (in the case of UML Activities, that animation would basically show the flowing of tokens through the Activity to be debugged). A first step in this direction has already been performed as part of a diploma thesis [Ban09].

If the verification shows that one of our VPPs does not hold for a particular model, the model checker will produce a counter example showing under which circumstances the violation of the VPP occurs. That counter example is expected to be very helpful for the business analyst when fixing the model’s flaws. Using the visual debugger as described in the previous paragraph, we want to back-propagate that counter example to the business analyst in an intuitive, easily understandable way.

Finally, we plan to visually model the soundness requirements against UML Activities identified in [ESW07]. Having shown the general usefulness of our approach that way, we plan to perform a larger case study in the context of DMM and our notion of VPPs.

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Bibliography


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